











The Vector VS1000 is Hemisphere GNSS' premiere multi-GNSS, multi-frequency receiver designed specifically for the professional marine market. Providing precise heading, Athena RTK positioning, and full Atlas capability, its rugged design is compliant to 60529:2013 IP67 and IEC 60945:2002 8.7 standards.

The VS1000 supports antenna separations up to 10 meters, offering heading accuracy to 0.01 degrees RMS in addition to RTK position accuracy and full support for Hemisphere GNSS' Atlas worldwide L-band corrections.

Key Features

- Athena™ RTK and Atlas® L-band capable
- Extremely accurate heading (to 0.01° RMS)
- Multi-frequency GPS/GLONASS/BeiDou/Galileo
- Purpose-built for the most challenging environments
- Supports Ethernet, CAN, Serial, USB, Bluetooth, and Wi-Fi
- Powerful WebUI accessed via Wi-Fi plus a 128x64 display and 10 multi-color LEDs

GNSS Receiver Specifications

Vector GNSS RTK Receiver **Receiver Type:**

Signals Received: GPS, GLONASS, BeiDou, Galileo, & Atlas 3

Channels: 1059 **GPS Sensitivity:** -142 dBm

SBAS Tracking: 2-channel, parallel tracking **Update Rate:** 10 Hz standard, 20 Hz optional

Timing (1PPS)

Accuracy: 20 ns

Rate of Turn: 100°/s maximum

Cold Start: 60 s (no almanac or RTC) Warm Start: 30 s typical (almanac and RTC)

Hot Start: 10 s typical (almanac, RTC and position)

Heading Fix: 10 s typical (valid position)

Antenna Input

Impedance: 50 Ω

Maximum Speed: 1,850 mph (999 kts)

Maximum

Altitude: 18,288 m (60,000 ft)

Differential

Options: SBAS, Atlas (L-band), RTK

Accuracy

Positioning: RMS (67%) 2DRMS (95%)

Single Point: 1 2.4 m SBAS: 2 0.6 m

Atlas H10: 6 0.08 m 0.16 m

Atlas H30: 6 0.3 m Atlas Basic: 6 $0.5 \, \text{m}$

RTK: 1, 3 8 mm + 1 ppm 15 mm + 2 ppm Heading (RMS): 0.2° @ 0.5 m antenna separation

0.1° @ 1.0 m antenna separation 0.05° @ 2.0 m antenna separation 0.02° @ 5.0 m antenna separation 0.01° @ 10.0 m antenna separation

Pitch/Roll (RMS):

Heave (RMS): 30 cm (DGPS) 1,10 cm (Atlas) 1,6,

5 cm (RTK) 1,6

L-Band Receiver Specifications

Channels: 1525 to 1560 MHz

Sensitivity: -130 dBm Channel Spacing: 5 kHz

Satellite Selection: Manual or Automatic

Reacquisition

Time: 15 sec (typical)

3.

Depends on multipath environment, number of satellites in view, satellite geometry, no SA, and ionospheric activity
Depends on multipath environment, number of satellites in view, WAAS coverage and satellite geometry
Depends on multipath environment, number of satellites in view, satellite geometry, baseline length (for differential services), and ionospheric activity
Based on a 40 second time constant Hemisphere GNSS proprietary
Requires a Hemisphere GNSS subscription
CMR and CMR+ do not cover proprietary messages outside of the typical standard

Communications

1x CAN, 1x Ethernet, 1x USB, 1x 12-pin

multi-purpose (RS232, RS422, CAN, 1PPS,

Event Marker)

4800 - 115200 **Baud Rates:**

Radio Interfaces: Bluetooth 2.0 (Class 2), Wi-Fi 2.4 GHz

Correction I/O

Protocol: Hemisphere GNSS proprietary ROX

format, RTCM v2.3, RTCM v3.2, CMR7,

CMR+7

Data I/O Protocol: NMEA 0183, Hemisphere GNSS binary

Timing Output:

1PPS (CMOS, rising edge sync)

Event Marker

Input: Open drain, falling edge sync, $10 \text{ k}\Omega$, 10

pF load

Environmental

Operating

Temperature: -40°C to +70°C (-40°F to +158°F)

Storage

Temperature: -40° C to + 85°C (-40°F to + 185°F)

Humidity: 95% non-condensing **Enclosure:** ISO 60529:2013 for IPx6/IPx7

Vibration: IEC 60945:2002 Section 8.7 Vibration EMC: IEC 60945:2002, EN 301 489-1 V2.1.1,

EN 301 489-5 V2.1.1, EN 301 489-19 V2.1.0,

EN 303 413 V1.1.1

Mechanical

Dimensions:

No Plate: 23.2 L x 16.5 W x 7.9 H (cm)

9.1 L x 6.5 W x 3.1 H (in)

With Plate: 23.2 L x 21.4 W x 8.3 H (cm)

9.1 L x 8.4 W x 3.3 H (in)

Display: 128 x 64 Resolution Weight: 1.7 kg (3.8 lb)

Status Indications

(LED): Power, Primary Antenna, Secondary

Antenna, Heading, Quality, Atlas, Bluetooth, Wi-Fi, CAN, Ethernet

Power/Data

Connector: M12 CAN/Power, 12-pin multi-purpose,

RJ45, USB

Antenna

Connectors: BT/Wi-Fi

Aiding Devices

Gyro:

Provides fast reacquisition and reliable heading for short periods when loss

of GNSS has occurred

Tilt Sensors: Provide pitch, roll data and assist in fast

start-up and reacquisition of heading

solution



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